

INGRAM SCHOOL OF ENGINEERING

Background

Our PenBot product is a small autonomous vehicle which moves precisely on a flat poster board or whiteboard surface while creating line drawings. According to Purdue University, "Advances in technology continue to push the envelope in healthcare, travel, communication and education. The use of robotic and simulation technologies have proven themselves to be worthy components of available educational resources." ¹

¹ The use of Robotics and simulators in the education environment. Purdue University Online. (n.d.). Retrieved from https://online.purdue.edu/blog/education/robotics-simulators-education-environment

Design Requirements

- Must be autonomous
- The robot will complete drawings stored on internal memory
- A jpg or bmp file converter to make a line drawing that can be used by the bot to draw a version of the original
- An interactive mode where the pen bot can be controlled remotely and wirelessly using a game controller, phone, or tablet
- PenBot must not exceed \$30 in materials per unit
- Maximum Width and Length = 160mm (no height restriction)



PenBot Chassis

Includes:

- ✤ 3D printed two-wheel chassis
- Lighted power switch and three image selection buttons
- Autonomous indicator (green LED on Pico W) Blue LED to indicate when PenBot is drawing
- Pen holder with lift mechanism

The Team



Julian Perez

Annika Lopez Uyen Nguyen

Acknowledgments

Sponsor: Lee Hinkle Faculty Advisor: Mark Welker



Scan to access our App!

E2.07 Team BotCats PenBot: Line-Drawing Robot Annika Lopez (Project Manager), Uyen Nguyen, Julian Perez









in main.pv

Ease of User Interface Test Results

on Anvil

were given the Users following set of commands

code speaks to main.py

hotspot



command

ser	Press Circle	Complete Test	Outcome
	3.8 seconds	57.9 seconds	PASS
	7.0 seconds	63.43 seconds	It was expected users
	4.5 seconds	70.3 seconds	would be able to read and complete the tasks in under 4 minutes. The longest time to
	5.8 seconds	64.2 seconds	seconds.