TEXAS **INGRAM SCHOOL OF** ENGINEERING

Problem Statement

Vitesco Technologies' current mechanical material delivery process is completely manual with milk run drivers needing to visually observe material and quantity requirements on the production floor then return to the stockroom to de-trash and load racks/totes for their routes. This process is heavy on manpower, inefficient, and takes up excess space on the production floor.

Project Purpose

- Decrease Production Floor Clutter
- Increase Plant Efficiency
- Reevaluate Material Flow







De-trashing



Milk Run

Objectives/Evaluation

Product Functions:	Design Specifications (Performance Targets)
Cycle Time Data	Material Consumption Milk Run Routes De-Trashing
Data Analysis	Automatable Parts Determination Kanban Levels Efficiency of Process' Safety Cost Savings
Design (Stretch)	Warehouse Re-Design Milk Run Rerouting Production Floor Re-Design

Simulation



I 2.03 - Automated Milk Run Ordering System

Eric Brady, Rosa Rodriguez, BJ Iroha, Brandon Willis

Ingram School of Engineering



VILESCO TECHNOLOGIES

Human Factors

- •Loads should be kept under 51 lbs.
- •Loads should be kept close to the body, <25 in
- •Heavy totes should be kept at 30 in from the floor when lifting
- •Vertical distance from the floor should between 30 in and 70 in
- •Torso twisting should be minimized ,< 135°

 Assuming minimum Kanban maximums are desired; The minimum condition that we acquired only works for up to 3 unique products running at once.

• Assuming the Pallet Condition; where full detrash of individual pallets is desired then the Kanban Maximums will be much higher

Team Members

- From Left to Right
- BJ Iroha
- Rosa Rodriguez
- Brandon Willis
- Eric Brady

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