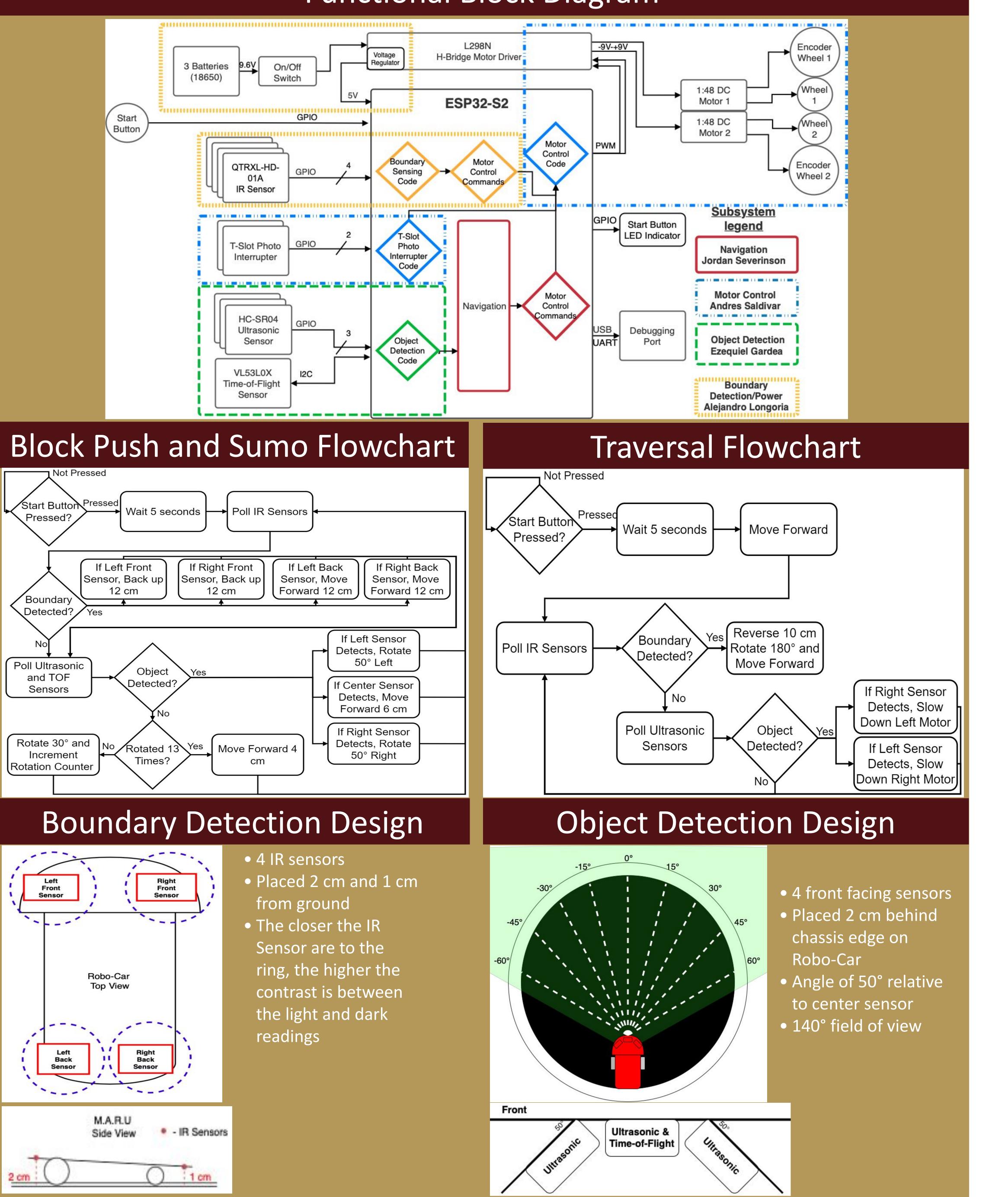


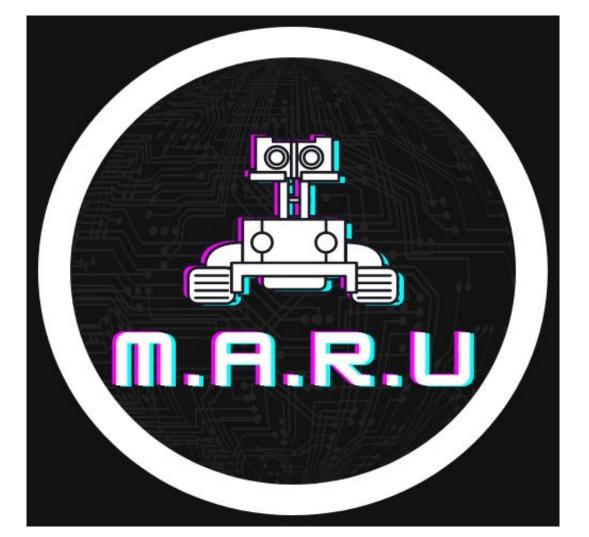
# E2.09 - Project M.A.R.U

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M.A.R.U is an autonomous Robo-Car that is designed to detect objects and boundaries and navigate accordingly.

# Functional Block Diagram





### Test Cases

<u>Requirement</u>	<u>Criteria</u>
B Hour Minimum Battery Life	Pass: The Robo-Car stops functioning after 118 minutes of continuous use, so it will last 3 hours of non continuous usage
Block Push	Pass: 100% success rate with 0° - 15°, at 30°, the success rate is 80% for the medium and large blocks, 70% for the small block
Sumo Tournament	Pass: 100% success rate with 0° - 15° at all distances, 90% success rate at 30° and 30 cm, and 80% success rate at 30° and 60cm
Traversal competition	Pass: 100% success rate at 20 ft, 85% success rate at 30 ft, and 75% success rate at 40 ft

# **Power Dissipation**

ergy Source	Voltage (V)	Power (W-h)	
650 Lithium-Phosphate ttery (3)	9.8	14.4	
ergy Drain	Voltage (V)	Power (W-h)	
P32-S2	5.00	1.13	
98N Motor Driver	9.00	2.43	
CTT Motor(left)	7.80	1.29	
TT Motor(right)	7.70	1.26	
RXL-HD-01A (VCC) (4)	4.95	0.63	
lot Photo Interrupter (2)	4.97	0.29	
C-SR04(3)	4.95	0.22	
53L0X	4.83	0.09	
	Total	7.36	

# Acknowledgements

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