TEXAS $\because$ STATE
INGRAM SCHOOL OF ENGINEERING

## Background

Robotics is an expanding discipline in the engineering industry and has the potential to complete tasks with greater efficiency and provide an alternative to humans working dangerous jobs. This project will provide this group with valuable experience in robotics design and problem solving.

## Requirements

Single egg retrieval: The bot will need to be able to locate a single egg in the arena and retrieve it to the red starting square Multiple egg retrieval: The bot will need to be able to retrieve multiple eggs of one color in a field of eggs that are different colors.

| Budget |  |  |  |  |
| :--- | ---: | ---: | ---: | ---: |
| Part | Quantity | Price $/$ Unit | Total |  |
| EsP 32 CAM | 1 | 9.72 | 9.72 |  |
| Screws | 10 | 0.505 | 5.05 |  |
| TCRT 5000 |  | 2 | 0.88 | 1.76 |
| Pi Pico |  | 1 | 5 | 5 |
|  |  |  |  | 21.53 |

## Power Budget

| Micro Controllers / Sensors | 870 mA |
| :--- | :--- |
| L298N Driver and Motors | 470 mA |
| Total: | 1340 mA |

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- Chadd Mingarine
- Jacob Mitchell


## E 1.08 - Humpty Dumpty's White Knights

Weston Dilling, Juan Castillo, Mohammad Chikhani, Riley Duncan


KNIGHTS


Camera View


- Integrate all subsystems together
- Complete development of navigation subsystem
- Rigorous testing of all subsystems and whole unit

