# TEXAS STATE UNIVERSITY. Ingram School of Engineering

# E1.09 - Vertical Minds

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Sponsor: Mr. Sercan Iscan



# Design Overview

Our project will demonstrate a horizontal model that mimics the functionality of an elevator. This project will be coded using PLC(Programmable Logic Control) with OpenPLC which consists of floor selection, door operation, & user interface.

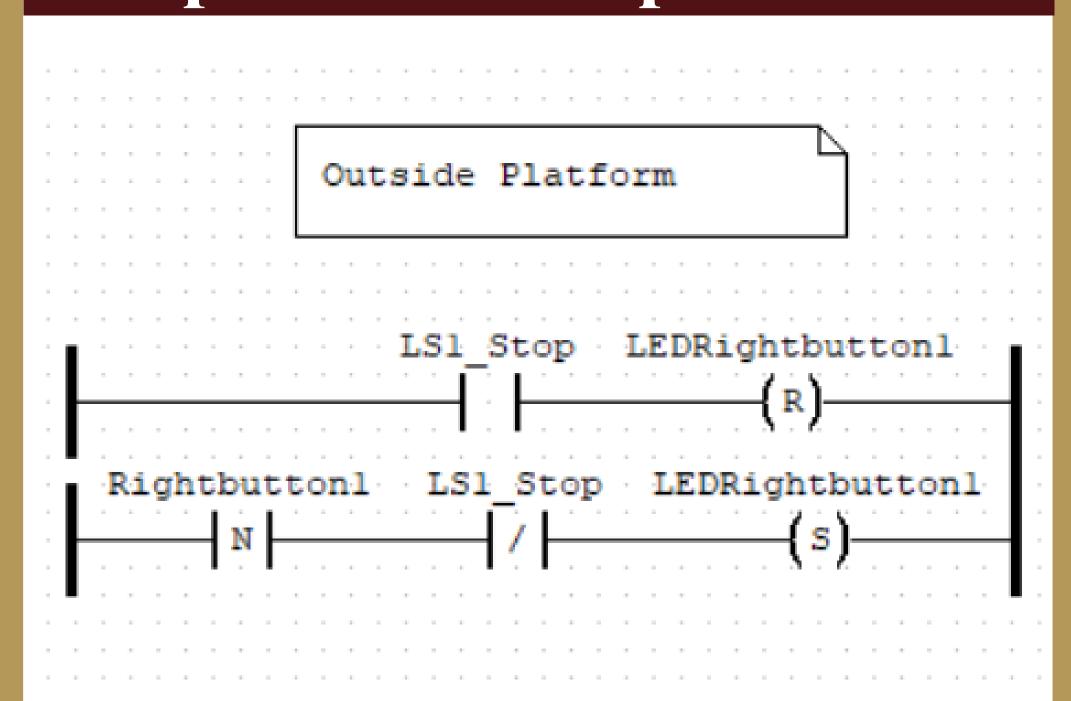
# D1 Requirements

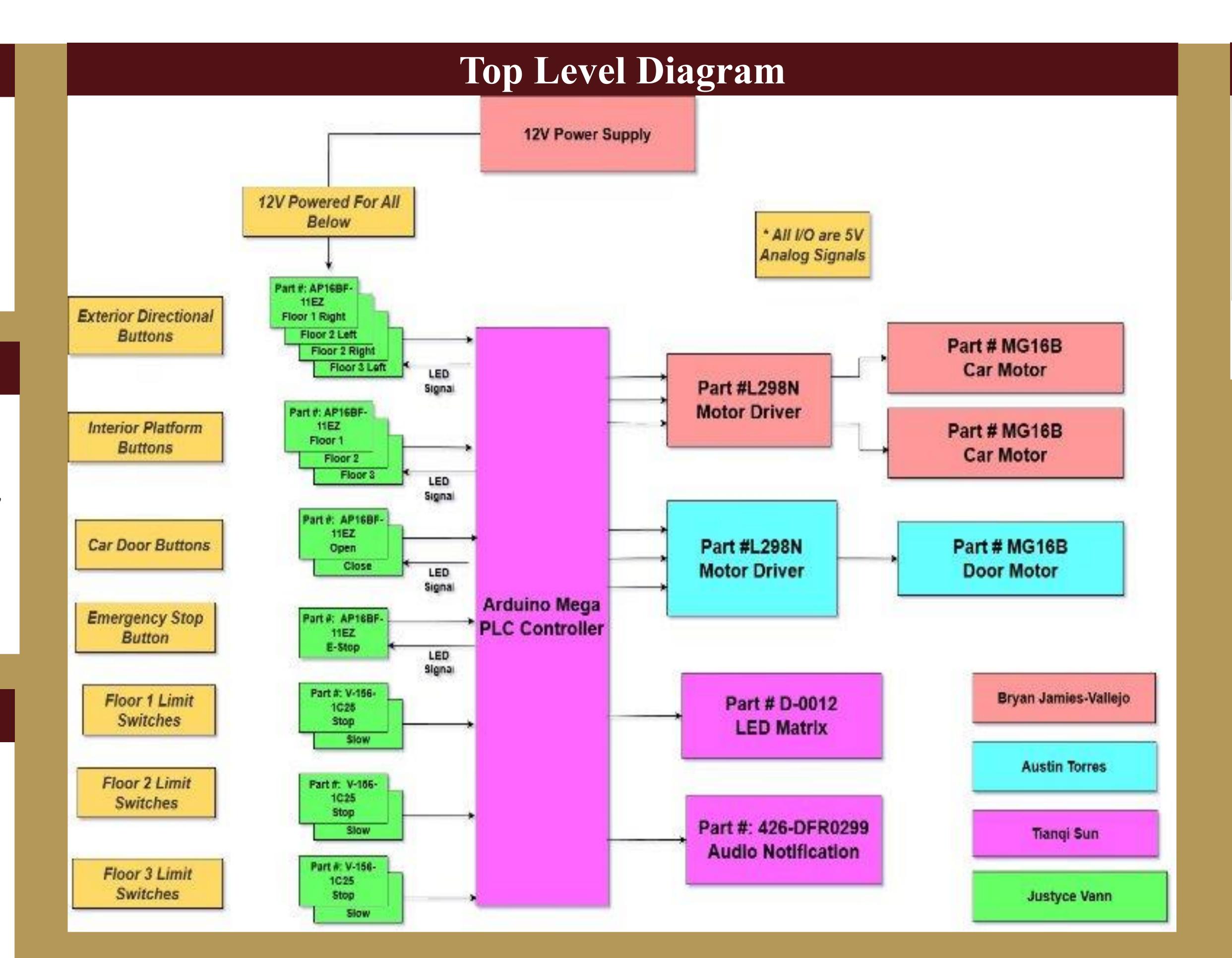
- Individual Sub-system functionality demonstrated by simulation in OpenPLC
- Simulation demonstrating button response, car motor activation/direction, car door operation and sensor input
- Documentation of planned hardware implementation and controller(s) selection

### D1 Achievements

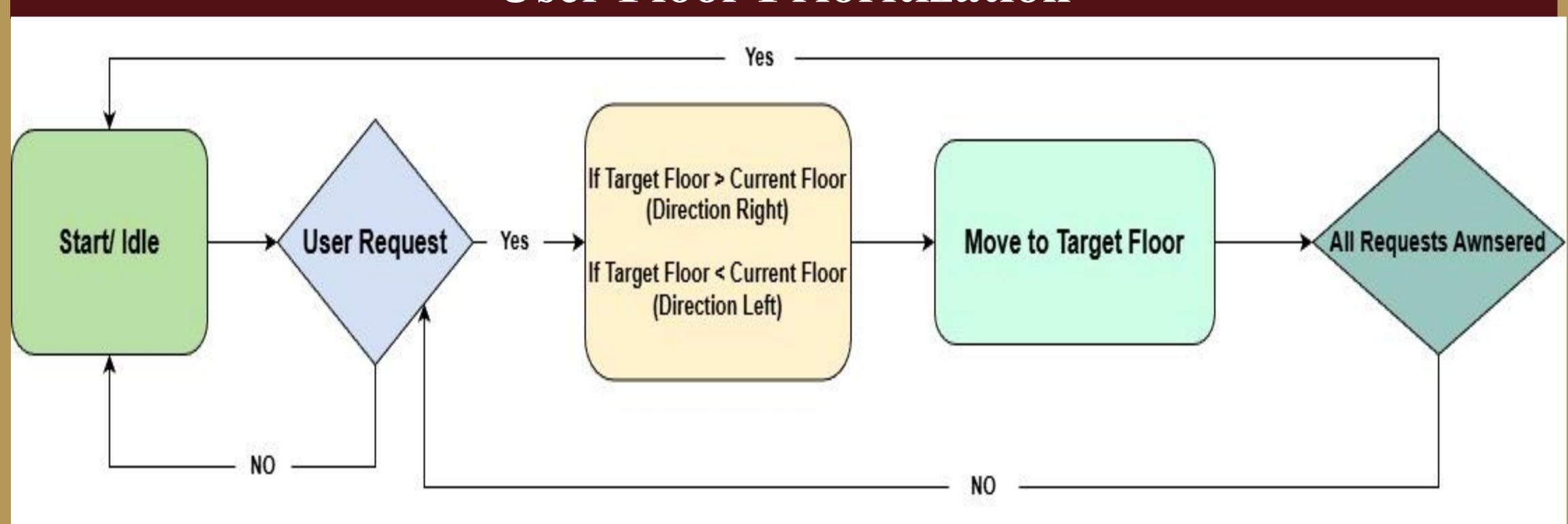
- Requirements for D1 were met
- Subsystems were wired on the breadboard using Arduino Mega
- Physical model was built, and each subsystem is being implemented in the actual physical model

# OpenPLC Sample Code





# User Floor Prioritization



#### Meet The Team



Justyce(PM) Floor Selection

Bryan Control

Austin Status Feedback Operation User Interface

D2 Plans

- Full design, integration, and working model
- Demonstrating button response, car motor activation/direction, car door operation and sensor input
- Optimization of elevator movement and floor wait time

#### 3D Model

3D Model was designed using **Autodesk Fusion** 



# Acknowledgements

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- D2 Mentor Team: 2.01 TSGC ILCS-2