



E2.01 - Integrated Camera and Lighting System Erika Griffin, Jonah Hartley, Collin Peters Lights, Camera, Bobcats!

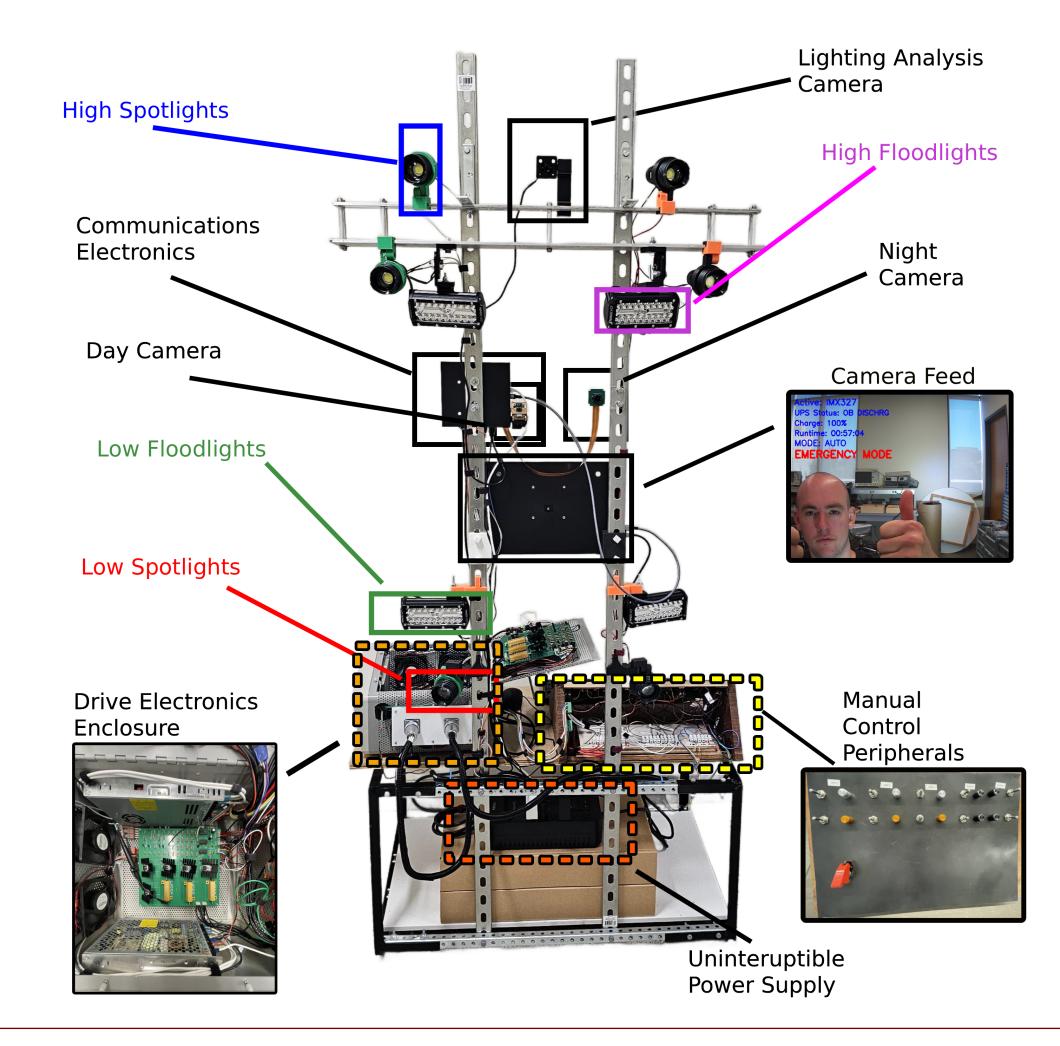


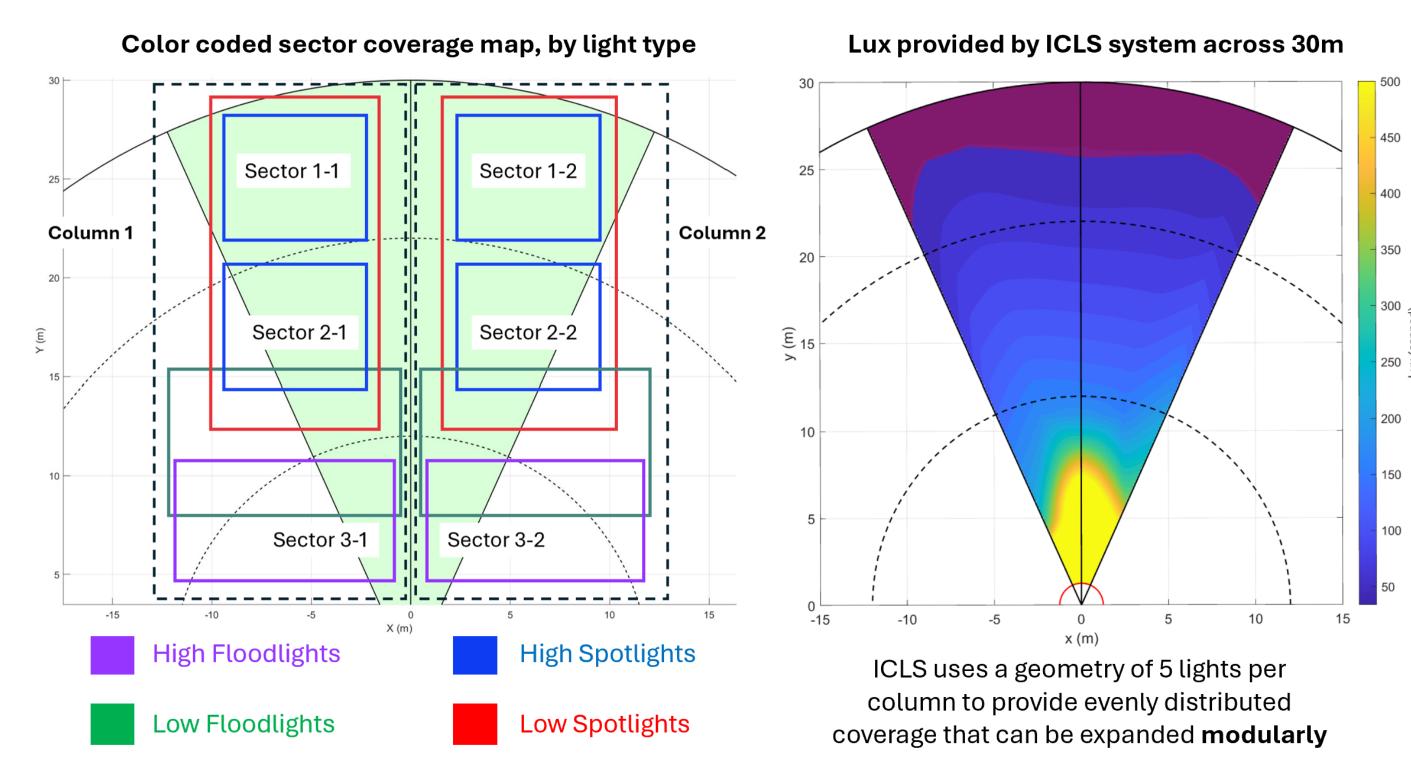
Problem Description

NASA's upcoming missions to the lunar surface present extreme contrast lighting conditions, from brilliant sunlight to deep, dark shadows. Traditional lighting systems force a trade-off between underexposure and power efficiency, while many existing Pulse Width Modulation systems used to drive LEDs are incompatible with video capture. Future exploration also demands real-time monitoring for both astronaut safety and mission efficiency.

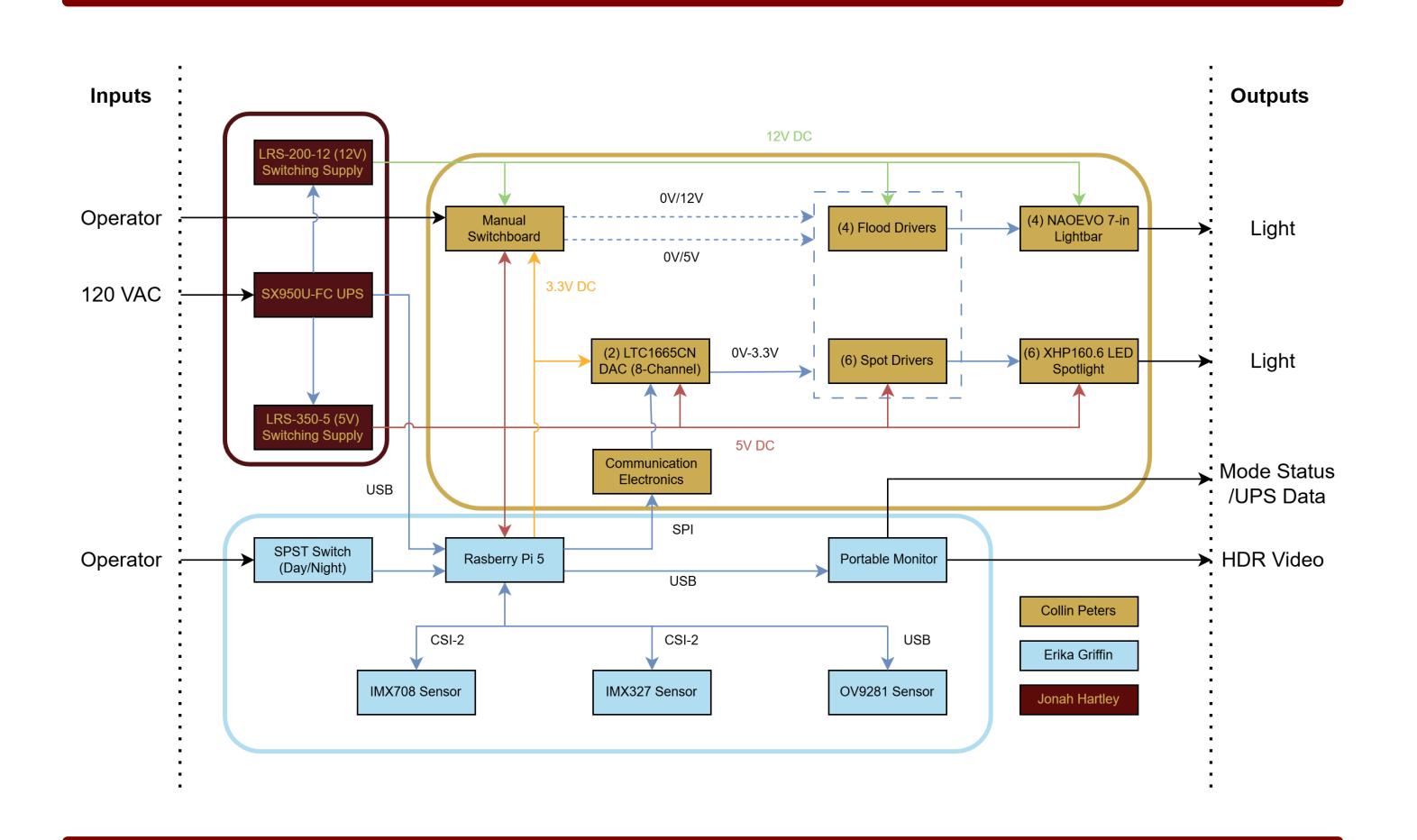
Our Solution

- A Raspberry Pi 5 analyzes sector brightness in real time.
- Only the necessary lights are activated to maintain safe illumination.
- Manual override mode gives operators direct control when needed.
- Assumption of 4m/s top rover speed and 2 second required reaction time.
- Reliable power and cooling: UPS backup, emergency-mode, Pi 5 + driver cooling, and stable temps verified for 100-minute operation.



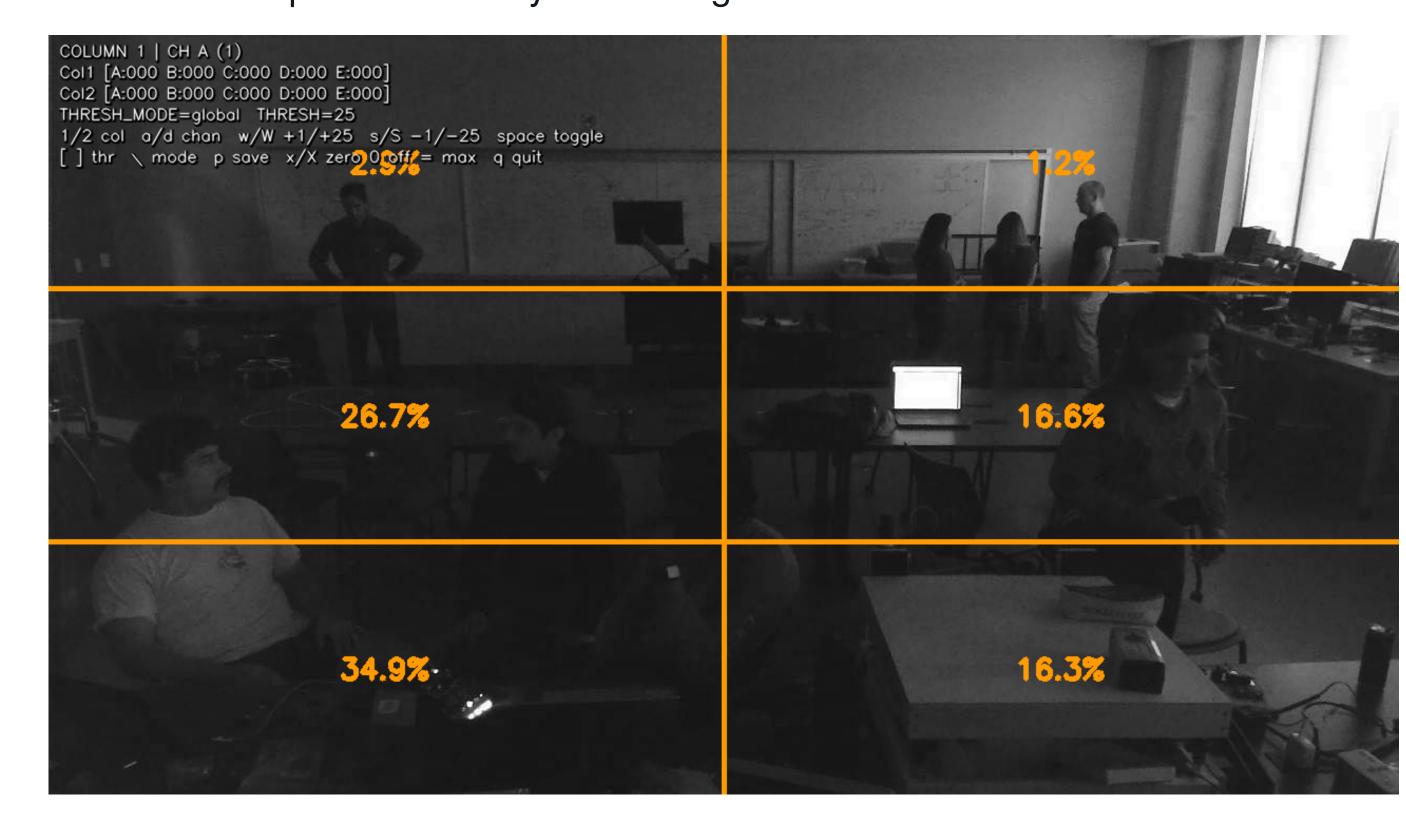


System Architecture & Top-Level Diagram



Real-Time Adaptive Illumination

- Arducam B0332 + HDR/low-light cameras for full-scene analysis
- Real-time sector-based % dark estimation
- Fast control loop activates only needed lights

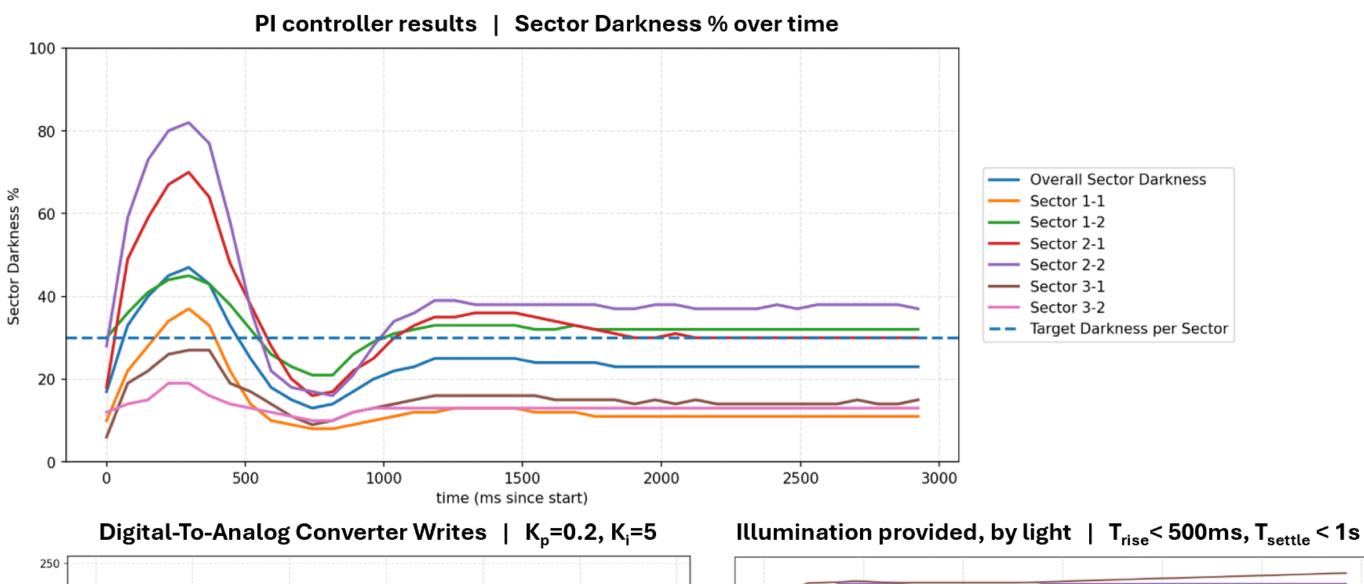


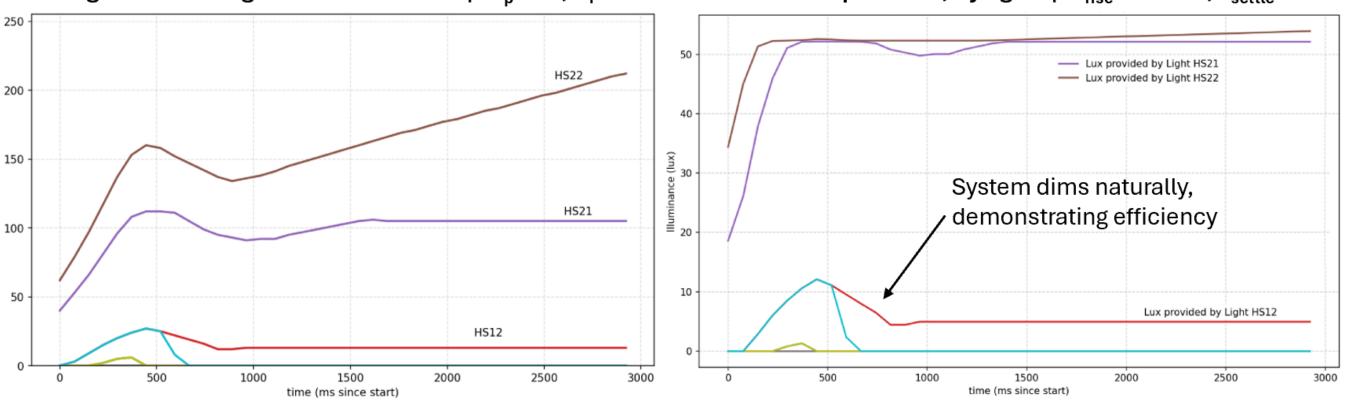
System Identification

- Pseudo-Random Binary Sequence (PRBS)
- Autoregressive Exogenous (ARX) Model (2 Poles, 1 Zero)
- Matlab tuned PI Controller provides smooth, stable lighting adjustments

System Controls & Response

- Effective lighting distance up to 25 meters
- 90 ms single-frame response time
- Under 500 ms rise time for rapid correction
- Energy-efficient: only necessary lights activate





Sector brightness values during a perturbation are displayed above. The system responds with a controlled rise and minimal oscillations before settling.

Meet the Team



Jonah Hartley, Collin Peters (Project Manager), Erika Griffin

Future Work & Acknowledgements

Future Work: MIMO, MPC, Optics

Acknowledgements:

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