

Key HW 9_1

1. Work problem 9.1

Problem 9.1

$$\begin{aligned}
 \frac{\partial f_1}{\partial z} &= -2Ab(z-vt)e^{-b(z-vt)^2}; \quad \frac{\partial^2 f_1}{\partial z^2} = -2Ab \left[e^{-b(z-vt)^2} - 2b(z-vt)^2 e^{-b(z-vt)^2} \right]; \\
 \frac{\partial f_1}{\partial t} &= 2Abv(z-vt)e^{-b(z-vt)^2}; \quad \frac{\partial^2 f_1}{\partial t^2} = 2Abv \left[-ve^{-b(z-vt)^2} + 2bv(z-vt)^2 e^{-b(z-vt)^2} \right] = v^2 \frac{\partial^2 f_1}{\partial z^2}. \checkmark \\
 \frac{\partial f_2}{\partial z} &= Ab \cos[b(z-vt)]; \quad \frac{\partial^2 f_2}{\partial z^2} = -Ab^2 \sin[b(z-vt)]; \\
 \frac{\partial f_2}{\partial t} &= -Abv \cos[b(z-vt)]; \quad \frac{\partial^2 f_2}{\partial t^2} = -Ab^2 v^2 \sin[b(z-vt)] = v^2 \frac{\partial^2 f_2}{\partial z^2}. \checkmark \\
 \frac{\partial f_3}{\partial z} &= \frac{-2Ab(z-vt)}{[b(z-vt)^2+1]^2}; \quad \frac{\partial^2 f_3}{\partial z^2} = \frac{-2Ab}{[b(z-vt)^2+1]^2} + \frac{8Ab^2(z-vt)^2}{[b(z-vt)^2+1]^3}; \\
 \frac{\partial f_3}{\partial t} &= \frac{2Abv(z-vt)}{[b(z-vt)^2+1]^2}; \quad \frac{\partial^2 f_3}{\partial t^2} = \frac{-2Abv^2}{[b(z-vt)^2+1]^2} + \frac{8Ab^2v^2(z-vt)^2}{[b(z-vt)^2+1]^3} = v^2 \frac{\partial^2 f_3}{\partial z^2}. \checkmark \\
 \frac{\partial f_4}{\partial z} &= -2Ab^2 z e^{-b(bz^2+vt)}; \quad \frac{\partial^2 f_4}{\partial z^2} = -2Ab^2 \left[e^{-b(bz^2+vt)} - 2b^2 z^2 e^{-b(bz^2+vt)} \right]; \\
 \frac{\partial f_4}{\partial t} &= -Abv e^{-b(bz^2+vt)}; \quad \frac{\partial^2 f_4}{\partial t^2} = Ab^2 v^2 e^{-b(bz^2+vt)} \neq v^2 \frac{\partial^2 f_4}{\partial z^2}. \\
 \frac{\partial f_5}{\partial z} &= Ab \cos(bz) \cos(bvt)^3; \quad \frac{\partial^2 f_5}{\partial z^2} = -Ab^2 \sin(bz) \cos(bvt)^3; \quad \frac{\partial f_5}{\partial t} = -3Ab^3 v^3 t^2 \sin(bz) \sin(bvt)^3; \\
 \frac{\partial^2 f_5}{\partial t^2} &= -6Ab^3 v^3 t \sin(bz) \sin(bvt)^3 - 9Ab^6 v^6 t^4 \sin(bz) \cos(bvt)^3 \neq v^2 \frac{\partial^2 f_5}{\partial z^2}.
 \end{aligned}$$

2. Work problem 9.4

Problem 9.4

The wave equation (Eq. 9.2) says $\frac{\partial^2 f}{\partial z^2} = \frac{1}{v^2} \frac{\partial^2 f}{\partial t^2}$. Look for solutions of the form $f(z, t) = Z(z)T(t)$. Plug this in: $T \frac{d^2 Z}{dz^2} = \frac{1}{v^2} Z \frac{d^2 T}{dt^2}$. Divide by ZT : $\frac{1}{Z} \frac{d^2 Z}{dz^2} = \frac{1}{v^2 T} \frac{d^2 T}{dt^2}$. The left side depends only on z , and the right side only on t , so both must be constant. Call the constant $-k^2$.

$$\left\{ \begin{array}{l} \frac{d^2 Z}{dz^2} = -k^2 Z \Rightarrow Z(z) = Ae^{ikz} + Be^{-ikz}, \\ \frac{d^2 T}{dt^2} = -(kv)^2 T \Rightarrow T(t) = Ce^{ikvt} + De^{-ikvt}. \end{array} \right\}$$

(Note that k must be *real*, else Z and T blow up; with no loss of generality we can assume k is *positive*.)

$$f(z, t) = (Ae^{ikz} + Be^{-ikz})(Ce^{ikvt} + De^{-ikvt}) = A_1 e^{i(kz+kv t)} + A_2 e^{i(kz-kv t)} + A_3 e^{i(-kz+kv t)} + A_4 e^{i(-kz-kv t)}.$$

The general linear combination of separable solutions is therefore

$$f(z, t) = \int_0^\infty [A_1(k)e^{i(kz+\omega t)} + A_2(k)e^{i(kz-\omega t)} + A_3(k)e^{i(-kz+\omega t)} + A_4(k)e^{i(-kz-\omega t)}] dk,$$

where $\omega \equiv kv$. But we can combine the third term with the first, by allowing k to run *negative* ($\omega = |k|v$ remains positive); likewise the second and the fourth:

$$f(z, t) = \int_{-\infty}^\infty [A_1(k)e^{i(kz+\omega t)} + A_2(k)e^{i(kz-\omega t)}] dk.$$

Because (in the end) we shall only want the *real part* of f , it suffices to keep only *one* of these terms (since k goes negative, both terms include waves traveling in both directions); the second is traditional (though either would do). Specifically,

$$\text{Re}(f) = \int_{-\infty}^\infty [\text{Re}(A_1) \cos(kz + \omega t) - \text{Im}(A_1) \sin(kz + \omega t) + \text{Re}(A_2) \cos(kz - \omega t) - \text{Im}(A_2) \sin(kz - \omega t)] dk.$$

The first term, $\cos(kz + \omega t) = \cos(-kz - \omega t)$, combines with the third, $\cos(kz - \omega t)$, since the negative k is picked up in the other half of the range of integration, and the second, $\sin(kz + \omega t) = -\sin(-kz - \omega t)$, combines with the fourth for the same reason. So the general solution, for our purposes, can be written in the form

$$\tilde{f}(z, t) = \int_{-\infty}^\infty \tilde{A}(k) e^{i(kz - \omega t)} dk \quad \text{qed (the tildes remind us that we want the real part).}$$